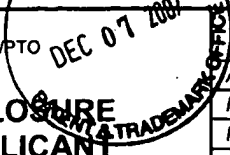


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IDS Form PTO/SB/08: Substitute for form 1449A/PTO

Complete if Known

INFORMATION DISCLOSURE STATEMENT BY APPLICANT <i>(Use as many sheets as necessary)</i>		Application Number	10/587,544		
		Filing Date	July 28, 2006		
		First Named Inventor	Takashi YAMAMOTO et al.		
		Art Unit	2837		
		Examiner Name	Paul Ip		
Sheet	1	of	1	Attorney Docket Number	09227.0014

U.S. PATENTS AND PUBLISHED U.S. PATENT APPLICATIONS					
Examiner Initials	Cite No. ¹	Document Number	Issue or Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
		Number-Kind Code ² (if known)			

Note: Submission of copies of U.S. Patents and published U.S. Patent Applications is not required.

FOREIGN PATENT DOCUMENTS						
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		Country Code ³ Number ⁴ Kind Code ⁵ (if known)				

NON PATENT LITERATURE DOCUMENTS			
Examiner Initials	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	Translation ⁶
/IP/		Japanese Office Action dated August 7, 2007	No
/IP/		K. Nagasaka et al., "Stabilization of Dynamic Walk on a Humanoid Using Torso Position Compliance Control," <i>17th Conference of Robotics Soc. Jap.</i> , Japan Robotics Society, Sept. 9, 1999, pp. 1193-94	Abstract
/IP/		K. Satoshi, "Design and Implementation of Remotely Operation Interface for Humanoid Robot," <i>Proc. 2001 IEEE Intl. Conf., Conference on Robotics & Automation</i> , Seoul Korea, May 21-26-2001, pp. 401-406	Yes

Examiner Signature	/Paul Ip/	Date Considered	1/14/2008
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EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.